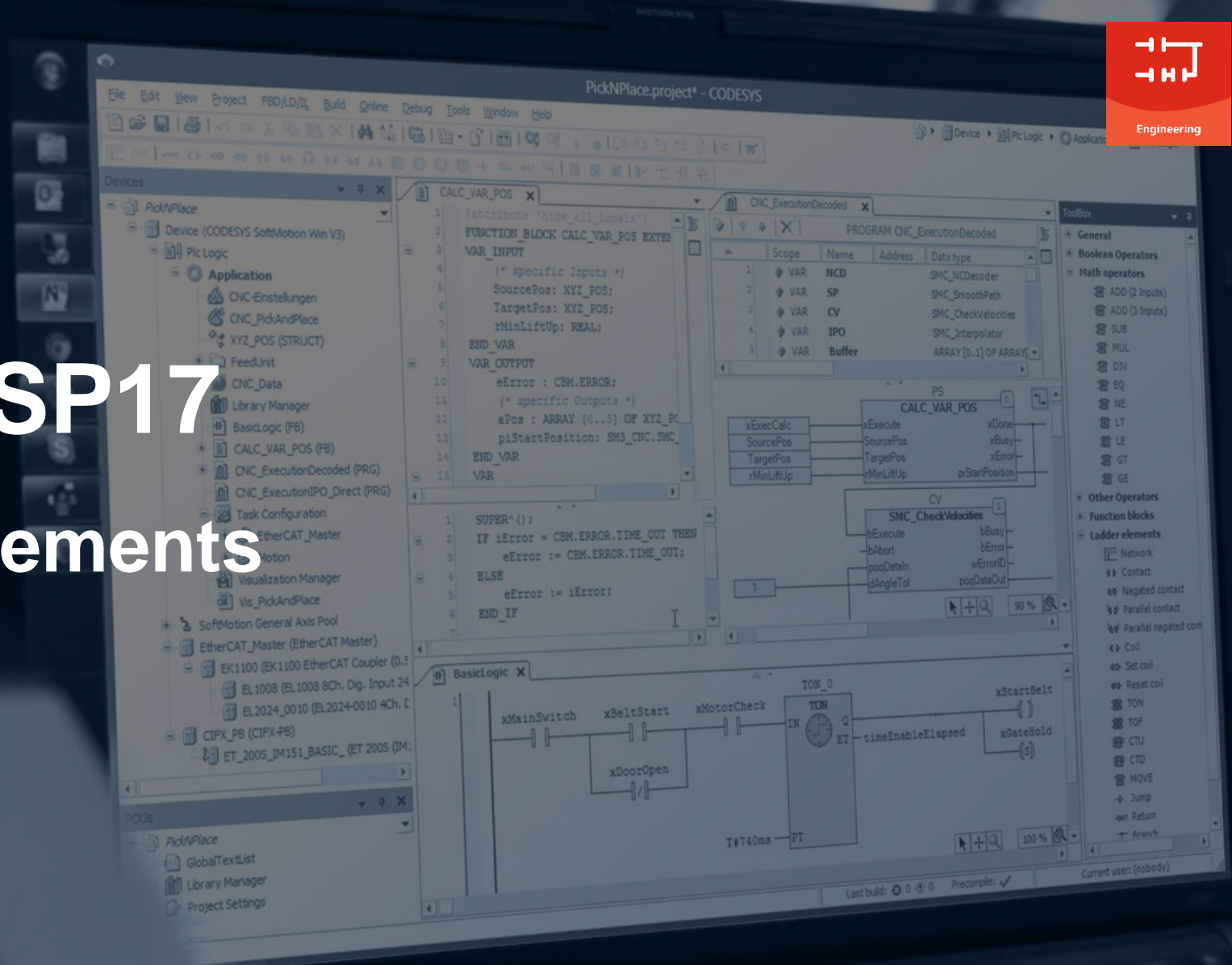




CODESYS V3.5 SP17

Features and Improvements



1

Engineering

2

Runtime

3

Visualization

4

Motion CNC Robotics

5

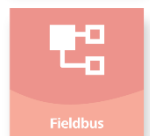
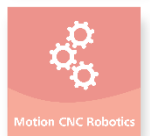
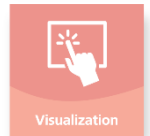
Fieldbus

6

Communication

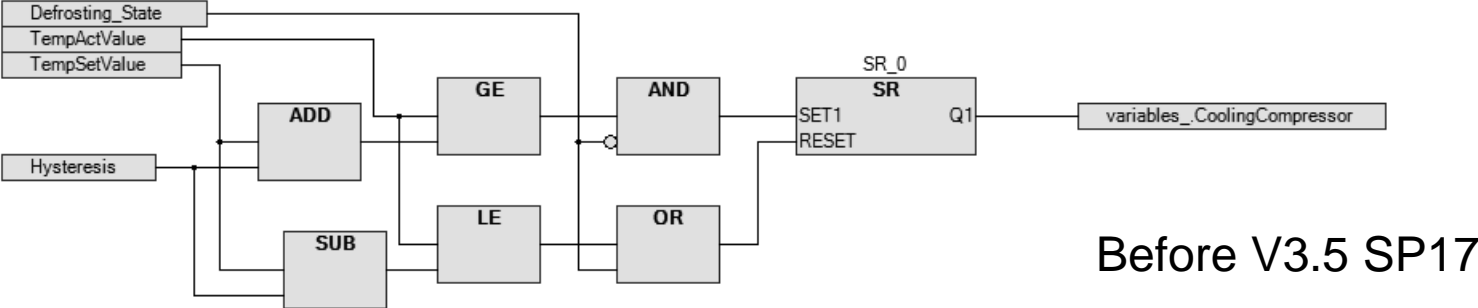
Overview

- **CFC improvements**
- **Security improvements**
- **Signed Libraries / Library Manager**
- **Further improvements**
- **Modularization of the CODESYS Development System**

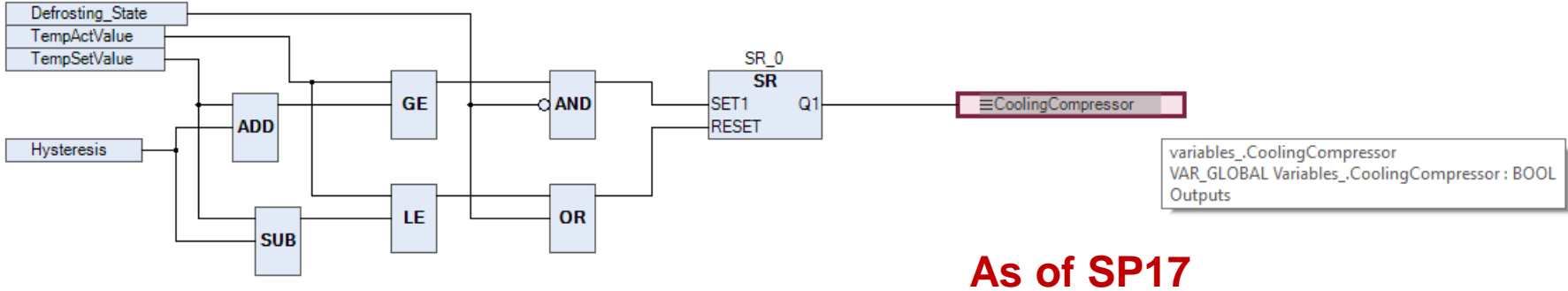


CFC improvements

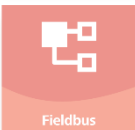
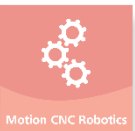
General space optimization



Signal_management Defrosting



Signal_management Defrosting

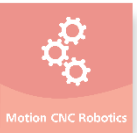
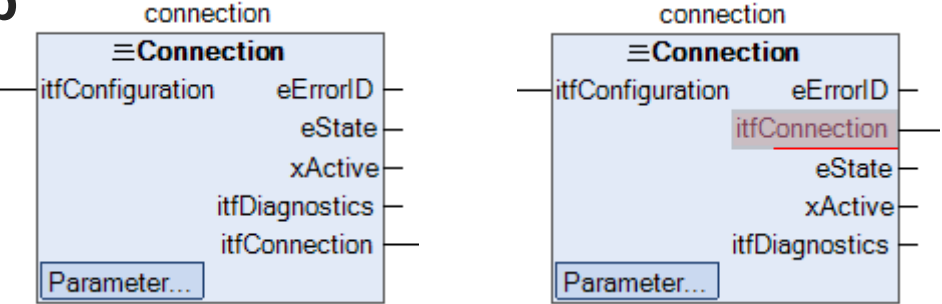


CFC improvements

- Dark theme

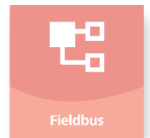
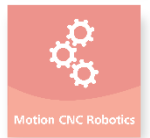
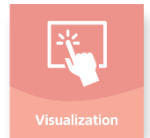
```
1 PROGRAM PLC_PRG
2 VAR
3   SR_0: SR;
4   Hysteresis: REAL:=1.0;
5   Valve1:MyValveType;
6   Valve2:MyValveType;
7   Ampel1:DUT;
8   Ampel2:DUT;
9 END_VAR
```

- Pin rearrangement by drag and drop



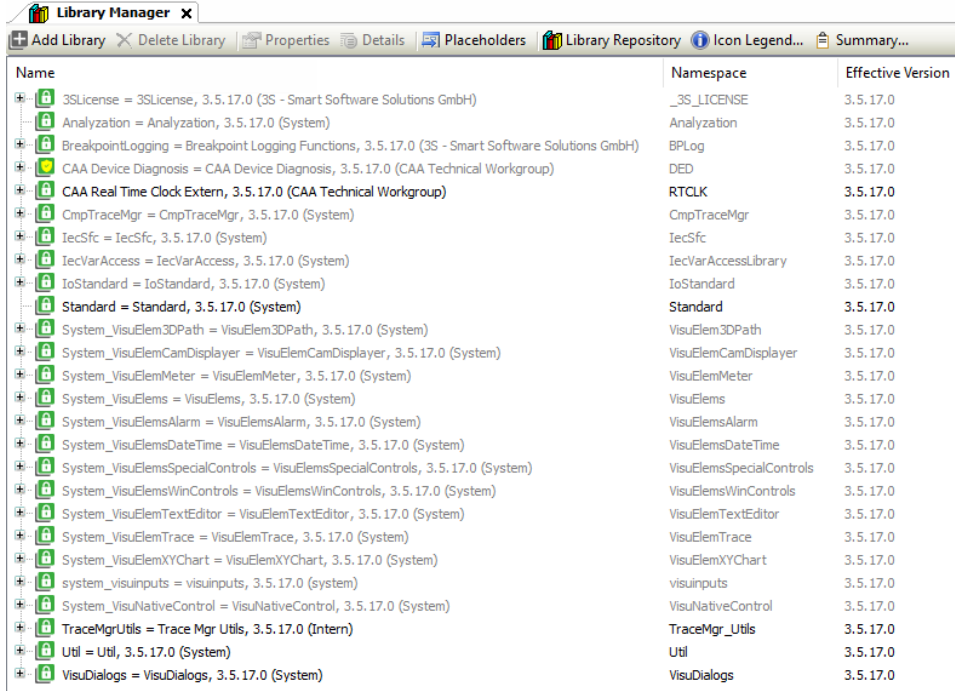
CFC improvements

- Increased drop area for connections
- Keyboard shortcuts
- Dropping objects and symbols into the canvas

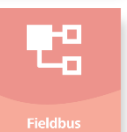
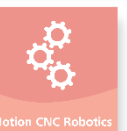
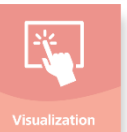
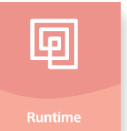


Signed libraries

- **Supported since CODESYS V3.5 SP15**
 - Simplification of former signing process with public/private key files
 - Now based on certificates
- **Unsigned libraries: now with restrictions in CODESYS**
 - No scripting in library documentation (since SP15)
 - Embedded files from unsigned libraries cannot be opened (new in SP17)
- **Signed CODESYS libraries**
 - In SP16: some
 - In SP17: all
(Exception: individual libraries with dependencies to libraries < SP17)

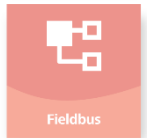
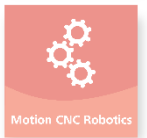
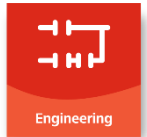
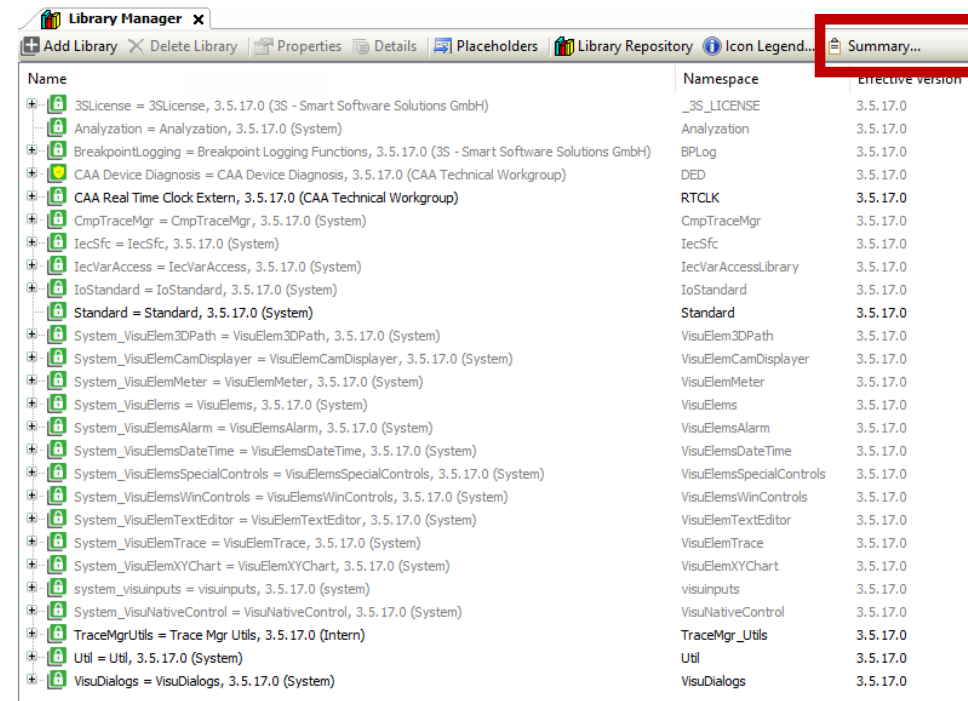
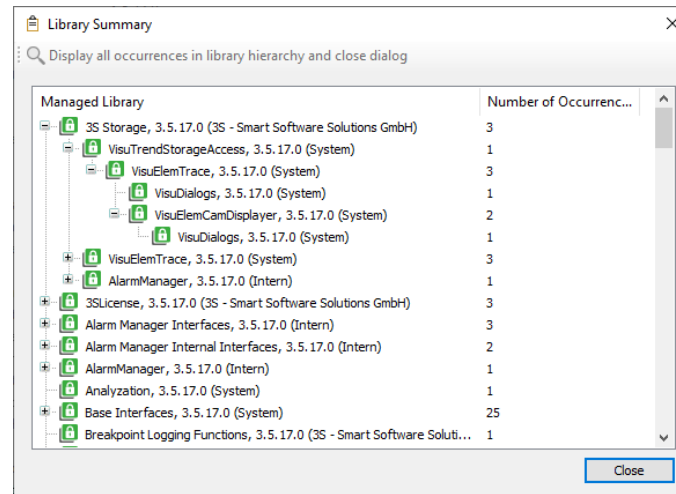


Name	Namespace	Effective Version
3SLicense = 3SLicense, 3.5.17.0 (3S - Smart Software Solutions GmbH)	__3S_LICENSE	3.5.17.0
Analysisation = Analysisation, 3.5.17.0 (System)	Analysisation	3.5.17.0
BreakpointLogging = Breakpoint Logging Functions, 3.5.17.0 (3S - Smart Software Solutions GmbH)	BPLog	3.5.17.0
CAA Device Diagnosis = CAA Device Diagnosis, 3.5.17.0 (CAA Technical Workgroup)	DED	3.5.17.0
CAA Real Time Clock Extern, 3.5.17.0 (CAA Technical Workgroup)	RTCLK	3.5.17.0
CmpTraceMgr = CmpTraceMgr, 3.5.17.0 (System)	CmpTraceMgr	3.5.17.0
IecSfc = IecSfc, 3.5.17.0 (System)	IecSfc	3.5.17.0
IecVarAccess = IecVarAccess, 3.5.17.0 (System)	IecVarAccessLibrary	3.5.17.0
IoStandard = IoStandard, 3.5.17.0 (System)	IoStandard	3.5.17.0
Standard = Standard, 3.5.17.0 (System)	Standard	3.5.17.0
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System_VisuElemCamDisplayer = VisuElemCamDisplayer, 3.5.17.0 (System)	VisuElemCamDisplayer	3.5.17.0
System_VisuElemMeter = VisuElemMeter, 3.5.17.0 (System)	VisuElemMeter	3.5.17.0
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System_VisuElemsWinControls = VisuElemsWinControls, 3.5.17.0 (System)	VisuElemsWinControls	3.5.17.0
System_VisuElemTextEditor = VisuElemTextEditor, 3.5.17.0 (System)	VisuElemTextEditor	3.5.17.0
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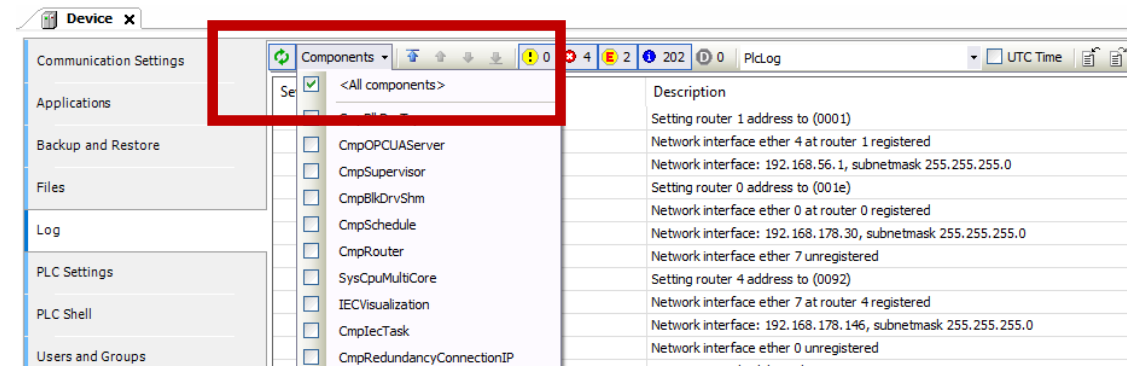
Library Manager

- New function in the Library Manager:
 Display of all transitively referenced
 libraries in the project**

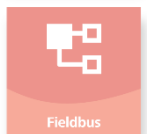
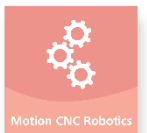
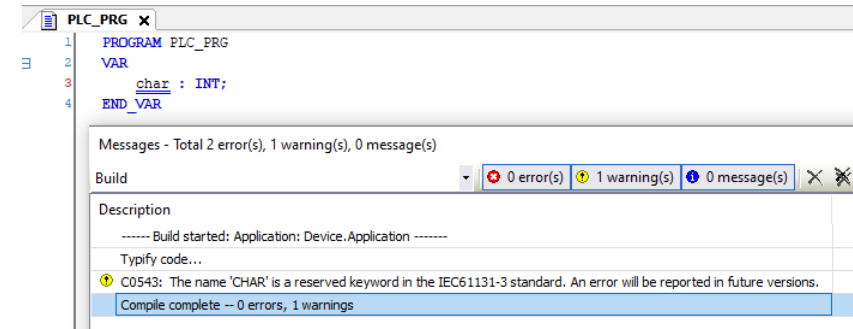


Further improvements

- **Compare:** Allow the comparison of two arbitrary objects
- **Logger:** Filter by component
➔ Improved usability

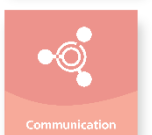
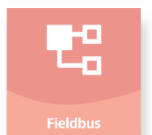
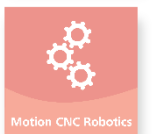
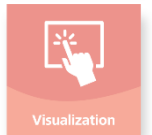
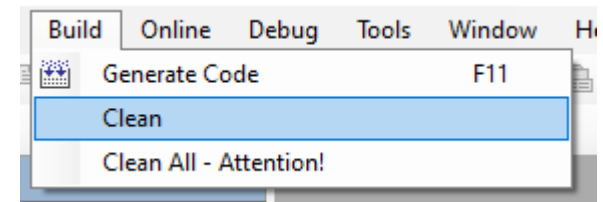


- **Preparation for new language features**
 - List of reserved keywords as of SP17
e.g. LDATE, CHAR, WCHAR
 - Usage ➔ Compiler warnings
 - Compiler errors as soon as new language features are available



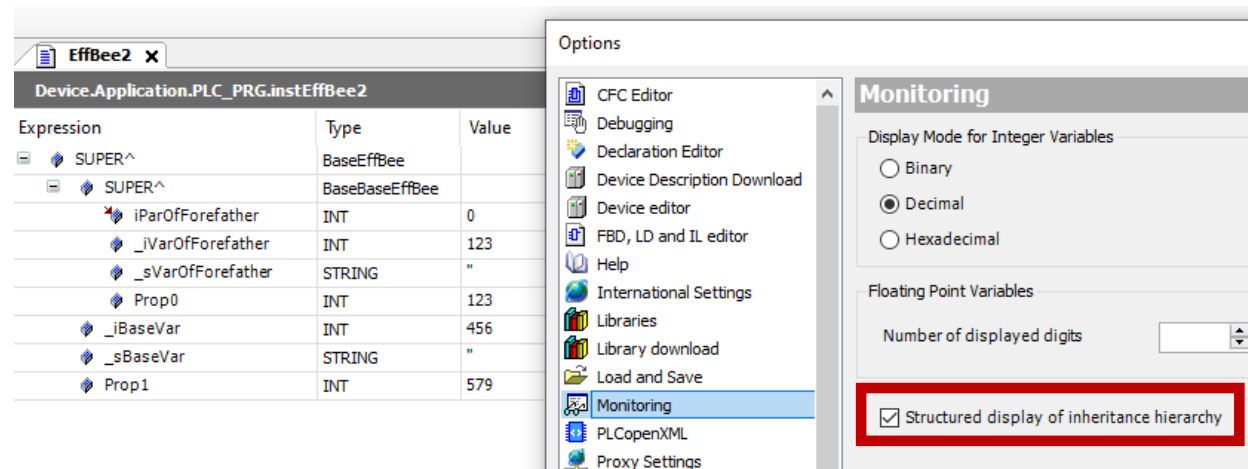
Further improvements

- **Acceleration of project load**
 - Language model stored as additional file (similar to compile information)
 - 15% - 35% faster loading of project files
- **General acceleration**
 - Blocking of certain operations avoided
 - Significantly faster reaction after project load / download
- **Re-work of the Build menu**
 - Easier usage
 - Former commands still available (via Customize command)



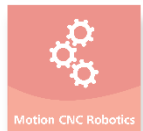
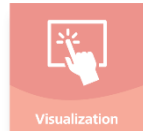
Further improvements

- Watch list:**
Structured display of inherited variables of an FB



- Force list:**
Display of recent process value of a forced variable

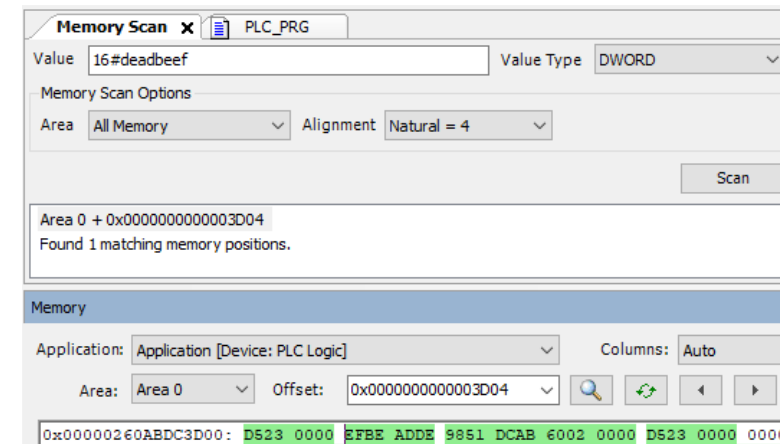
Expression	Type	Value	Prepar...	Overwritten value at start of cycle	Overwritten value at end of cycle
Device.Application.PLC_PRGj	DINT	F 55		55	1923
Device.Application.PLC_PRG.inst_di	DINT	F 78		78	1923



Further improvements

- Memory view: Search for specific values in the memory of the IEC application

- Supported in Core Dump, too

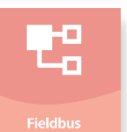
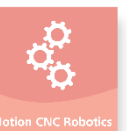
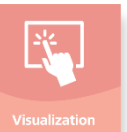
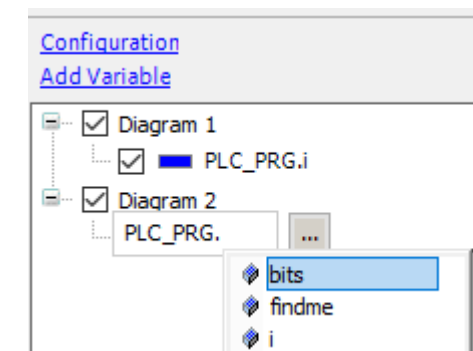


- Trace

- Simplified adding and editing of variables
- Improved work with multiple diagrams
- Improved usage of cursor

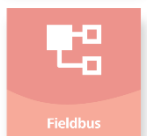
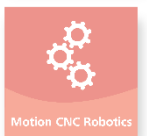
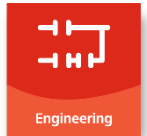
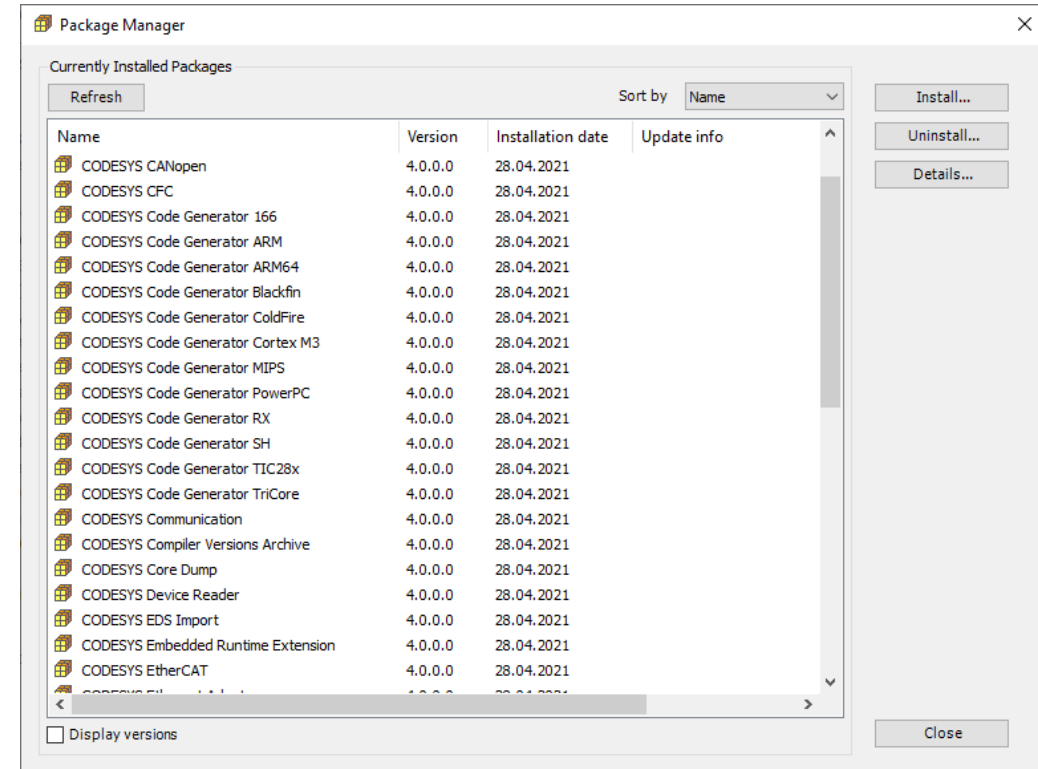
Configuration
Add Variable

Name	Cursor 1	Cursor 2	Delta
Diagram 1			
<input checked="" type="checkbox"/> PLC_PRG.i	38693	38699	Δ6
Diagram 2			
<input checked="" type="checkbox"/> PLC_PRG.j	38693	38699	Δ6



Modularization of the CODESYS Development System

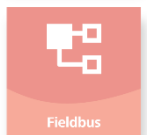
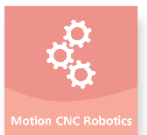
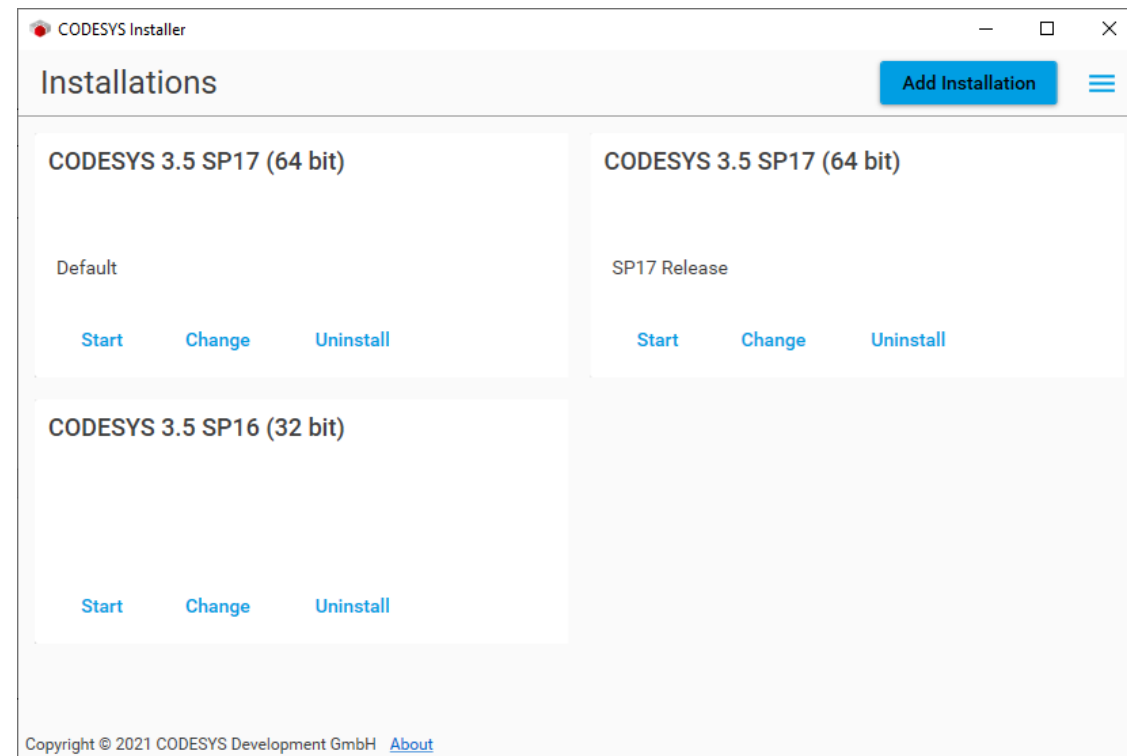
- **CODESYS Development System**
 - Unmodifiable core system: "CODESYS Essentials"
 - Mandatory in order to work
 - Various individual modules
 - Installed with the standard setup
 - Own versioning (4.x.x.x)
 - Update of individual modules possible without changing "CODESYS Essentials"
 - Functional updates at any time
 - Immediate benefit from improvements



Modularization of the CODESYS Development System

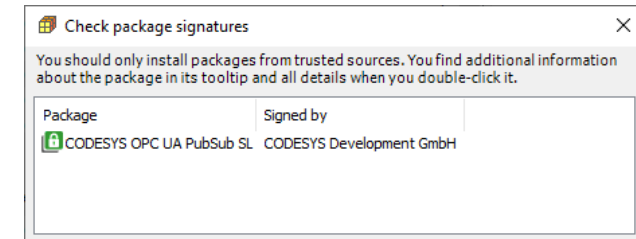
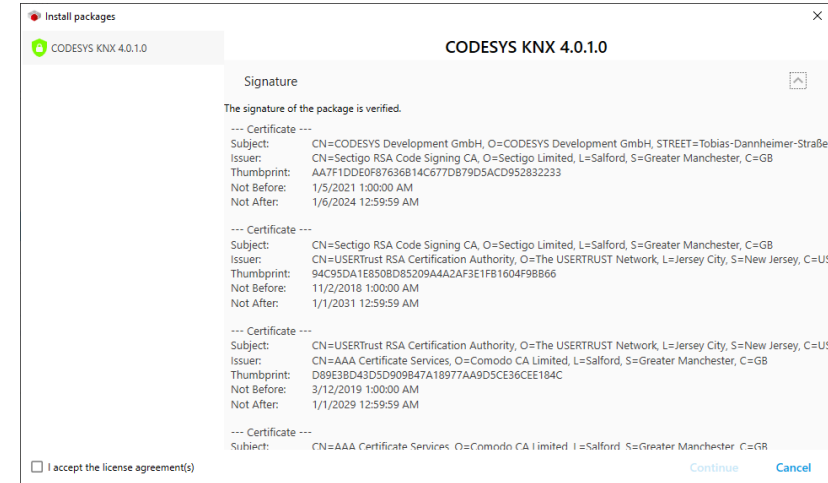
■ CODESYS Installer

- New executable delivered with the setup
- Grouping of required add-on components into so-called "installations"
- Creating customized versions with only desired components
- Simultaneous usage of versions for productive and experimental use
- Reload of missing components possible
→ Deployment server



Modularization of the CODESYS Development System

- **Signed add-on Packages**
 - All packages with native CODESYS add-ons are signed
→ Packages can be trusted.
 - Check within the CODESYS Installer and the Package Manager
 - Result similar to signed libraries
 - **Green:** Certificate / time stamp **certificate by a CA**
→ Both certificates are valid and not expired.
→ Package can be installed without any concern.
 - **Yellow:** Certificate is **self-signed, not signed or expired**, timestamp is not trustworthy.
→ Package can only be installed after user confirmation.
 - **Red:** Certificate does not match the content.
→ Package cannot be installed.



Engineering



Runtime



Visualization



Motion CNC Robotics



Fieldbus



Communication

1

Engineering

2

Runtime

3

Visualization

4

Motion CNC Robotics

5

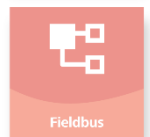
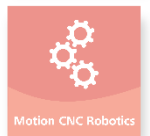
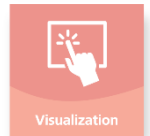
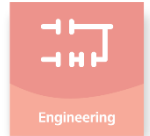
Fieldbus

6

Communication

Overview

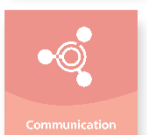
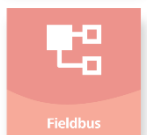
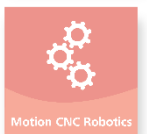
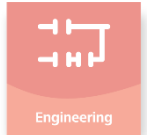
- **OPC UA Server/Client**
- **Firmware update**
- **Modularization**
- **Update CODESYS Control RTE SL**
- **Further improvements**



OPC UA Server / Client

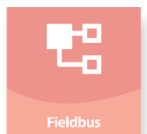
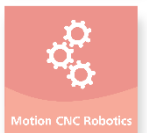
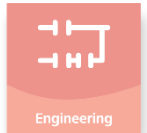
- Support of OPC UA Methods
- Support of OPC UA Alarms & Conditions
- Support of user-defined information models / companion specifications
- Implementation of new security profiles defined in OPC UA 1.04

Find detailed information in the section [Communication](#)



Firmware update

- **Backup / restore / update of the complete runtime system**
 - Main use cases
 - Update of the CODESYS runtime with backup of application, certificates, and licenses
 - Backup / restore of the CODESYS runtime including backup of application, certificates, and licenses
 - Introduction of a new „Device management service“ running stand-alone or as component of a runtime with backend for access to local and remote PLCs
 - Introduction of a generic archive format (including manifest and packages)
 - Other firmware parts (OS parts, drivers, external software) could be included, but not scope of development so far
 - Client implementation in development



Modularization

- **Independent releases of Linux-based single license runtimes**
 - Release of new features / improvements independent from main version (CODESYS Essentials)
 - Version changed to **V4.x.x.x**
 - No compatibility break
 - Runtimes still based on V3.5.x.x Runtime Toolkit



Wago Touch
Panels 600

Download >

CODESYS Control for V

This product allows users to program diff using the free CODESYS Development Sy:

Version: 4.1.0.0

Order number: 2302000038



Engineering



Runtime



Visualization



Motion CNC Robotics



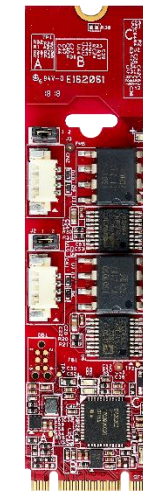
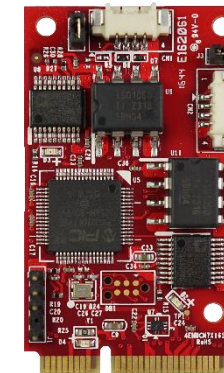
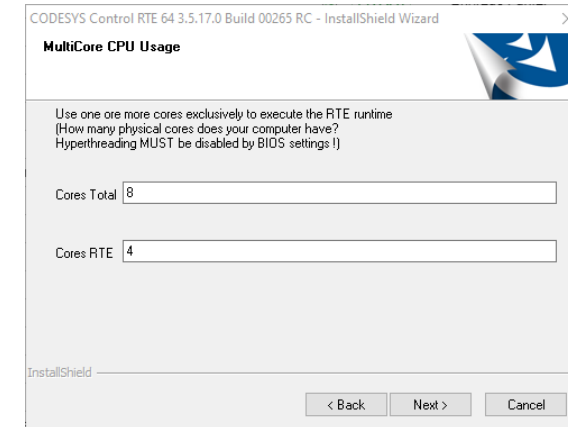
Fieldbus



Communication

Update CODESYS Control RTE SL

- **Multicore support**
 - Distribution of the application on multiple CPU cores
 - Selection of cores during setup
 - Task group configuration and core assignment within IDE
- **New drivers**
 - Support of new Peak CAN PCI Express cards
 - Support of Innodisk CAN PCI Express cards



Engineering



Runtime



Visualization



Motion CNC Robotics



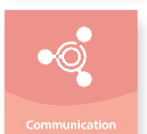
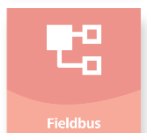
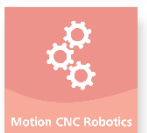
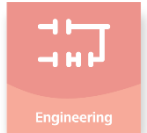
Fieldbus



Communication

Further improvements

- **CodeMeter®: Support of CodeMeter Universal Firm Code**
 - New generic firm code introduced by WIBU for all container types (dongle, SoftContainer, cloud)
 - Necessary for CodeMeter Runtime Support for Linux ARM
 - Due to compatibility issues only released for Linux ARM runtime
- **User Management**
 - Enable online user management by default
- **Integration of redundancy component in single-licensed runtimes**
- **Major update of CODESYS Control for PLCnext SL**
 - Bug fixes within Axioline configuration
 - Support of retain memory
 - Support of Smart Elements modules
 - Bug fix for problems with thread priorities
- **VxWorks**
 - Support of 64-bit targets on VxWorks 7



Further improvements

- Logging of user actions
 - Login successful / failed / logout
 - Download / create / start / stop / reset / delete application

Severity	Time Stamp	Description	Component
Info	19.05.2021 17:15:20.423	User: 'admin', Login (1)	CmpUserMgr
Info	19.05.2021 17:15:20.054	User: 'admin', Logout (0)	CmpUserMgr
Info	19.05.2021 17:15:19.994	User: 'admin', Login (1)	CmpUserMgr
Info	19.05.2021 17:15:17.104	User: 'admin', Logout (0)	CmpUserMgr
Info	19.05.2021 17:15:12.847	User: 'admin', Login (1)	CmpUserMgr
Info	19.05.2021 17:14:48.084	User: 'admin', Logout (0)	CmpUserMgr
Info	19.05.2021 17:14:47.988	User: 'admin', Login (1)	CmpUserMgr
Info	19.05.2021 17:14:46.841	User: 'admin', Logout (0)	CmpUserMgr
Info	19.05.2021 17:14:46.804	User: 'admin', Login (1)	CmpUserMgr
Info	19.05.2021 17:14:43.532	User: 'admin', Logout (0)	CmpUserMgr
Info	19.05.2021 17:14:35.584	User: 'admin', Login (1)	CmpUserMgr
Info	19.05.2021 17:14:34.448	User: 'admin', Logout (0)	CmpUserMgr
Info	19.05.2021 17:14:34.422	User: 'admin', Login (1)	CmpUserMgr
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Info	19.05.2021 17:14:26.167	System, App CodeGUID: 6d074fa4-0000-0000-0000-000000000000, DataGUID: 0...	CmpApp
Info	19.05.2021 17:14:26.167	System, App Download successful [Application], create bootproject: 0	CmpApp
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Info	19.05.2021 17:14:24.857	System, App CodeGUID: 6d074fa4-0000-0000-0000-000000000000, DataGUID: 0...	CmpApp
Info	19.05.2021 17:14:24.857	System, App Download successful [Application], create bootproject: 0	CmpApp
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Info	19.05.2021 17:14:24.854	System, App CodeGUID: 6d074fa4-0000-0000-0000-000000000000, DataGUID: 0...	CmpApp
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Info	19.05.2021 17:14:24.829	System, App CodeGUID: 6d074fa4-0000-0000-0000-000000000000, DataGUID: 0...	CmpApp

Auto scrolling: ON Displaying all available log entries.



Engineering



Runtime



Visualization



Motion CNC Robotics



Fieldbus



Communication

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Engineering

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Runtime

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Visualization

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Motion CNC Robotics

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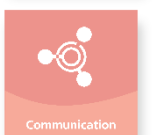
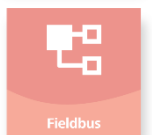
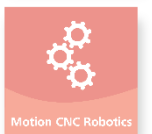
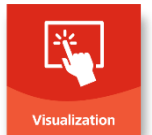
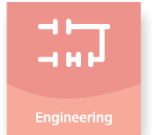
Fieldbus

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Communication

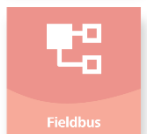
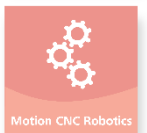
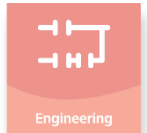
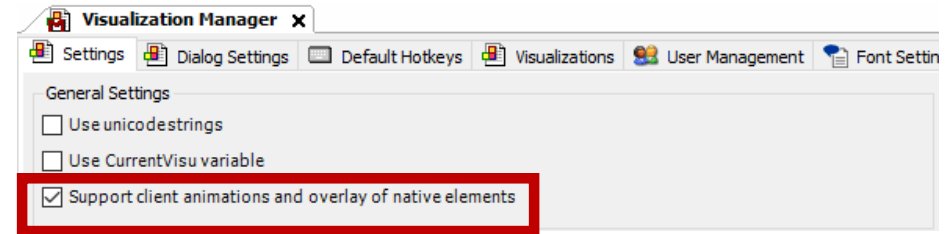
Overview

- **Overlay function in the CODESYS TargetVisu**
- **OPC UA Client support in CODESYS HMI SL**
- **HMI Redundancy**
- **Improvements of trend / alarm management**
- **Further improvements**



Overlay function in the CODESYS TargetVisu

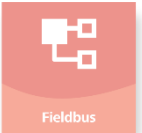
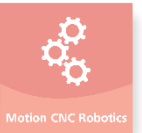
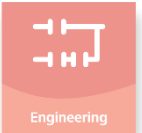
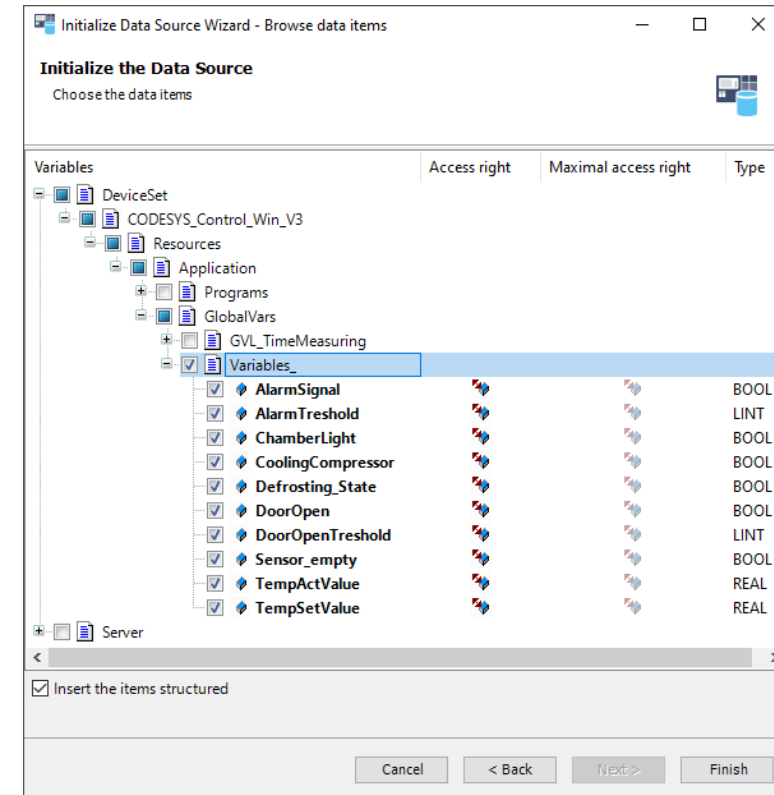
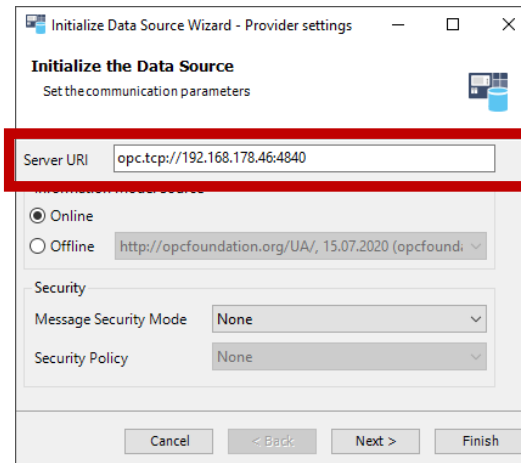
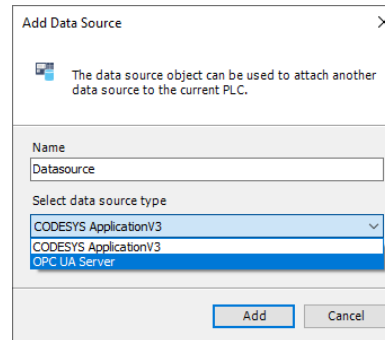
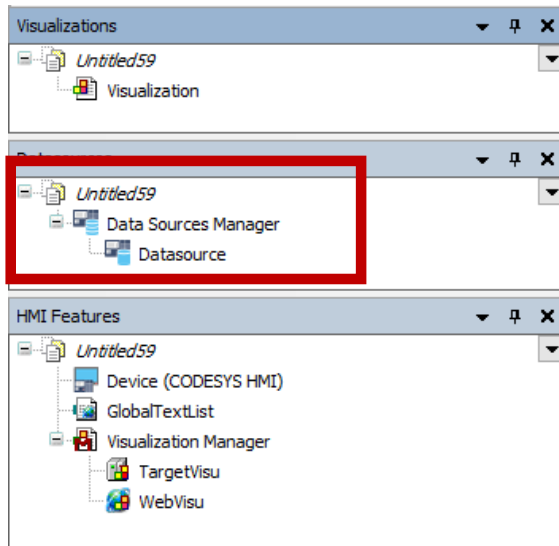
- **Dynamic internal rotation for all elements** (includes groups, frames, and native controls)
- **Time animations**
 - Smooth flying in of a menu independent of the visualization task
 - Smooth transitions for dialog fade in/out
 - Update of animated images such as GIFs/SVGs independently of the visualization task
- **Free positioning of elements in all dimensions**
 - Dialog opens over browser control
 - Crosshairs can be placed over camera image with visualization elements
- **Hardware accelerated drawing of TargetVisu (using GPU)**
- **Enabled by default in new projects - if supported by device**
- **Precondition: Qt installed on the target device**
- **For details, see video at <https://youtu.be/C-7RQW-jmDk>**



CODESYS HMI SL with OPC UA Client

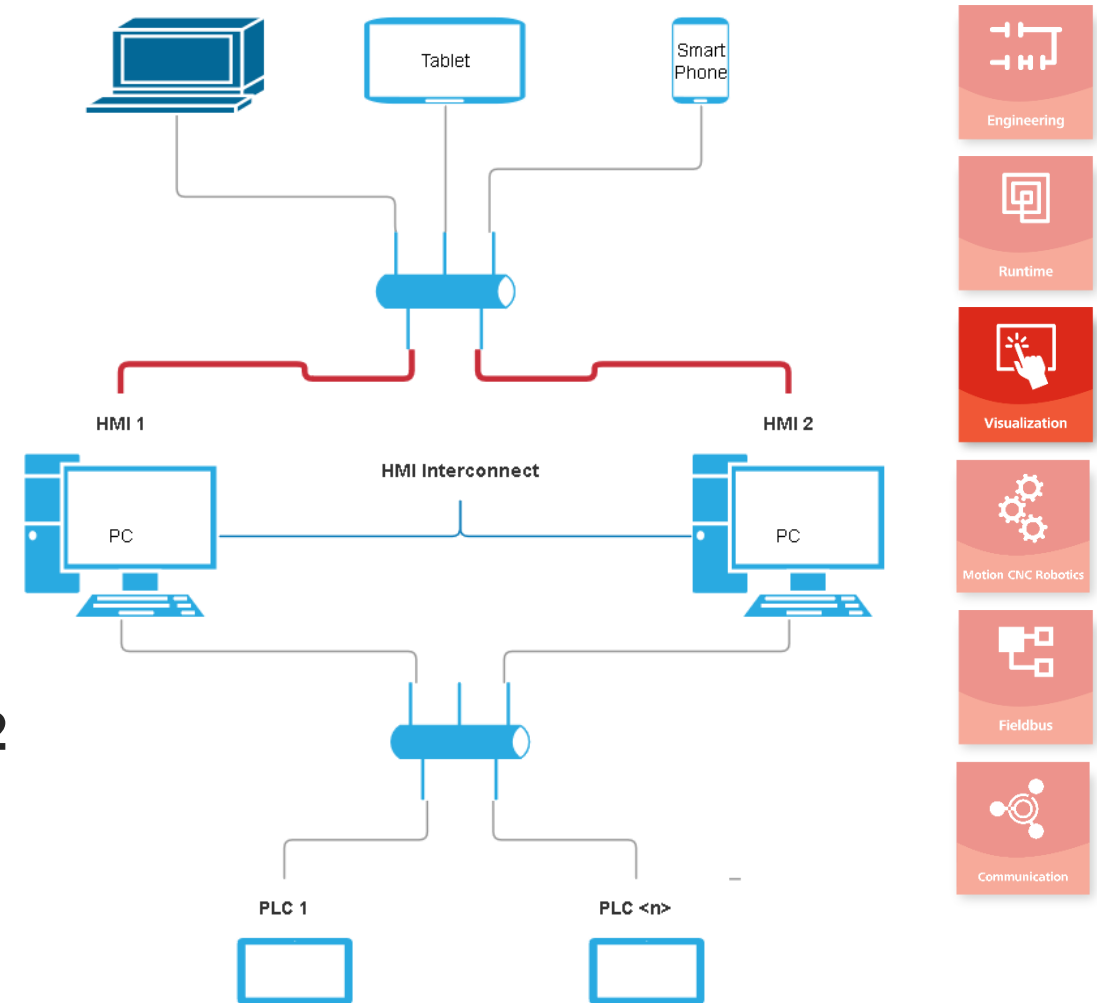
CODESYS HMI SL

- Connecting to available OPC UA server
- Browsing the published data
- Read / write access to the data via visualization






HMI redundancy

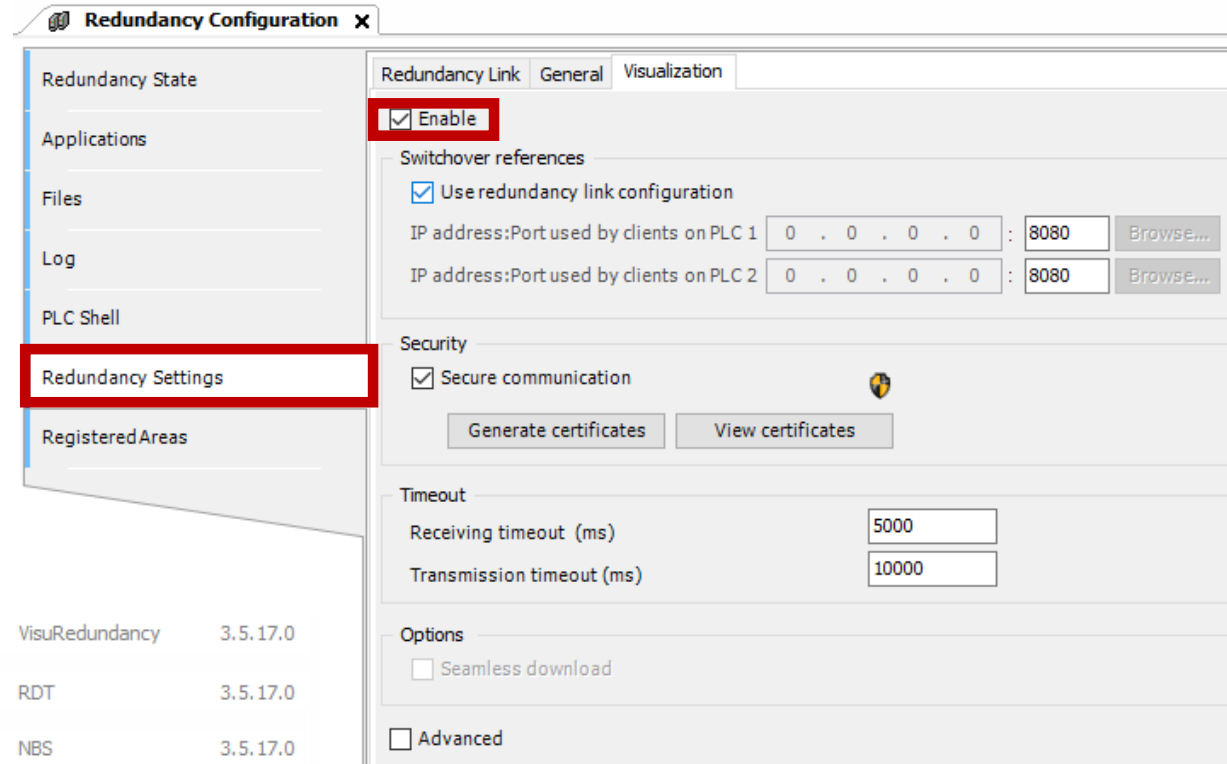
- Synchronization of WebVisu client information between HMI master and slave
- In case of failure of HMI master: All WebVisu clients are automatically switched to the other HMI
 - Clients remain on pages/frames as before.
 - Login remains
- Immediate start of data transfer from the new HMI master to the controllers
- Central display of alarms either in HMI1 or HMI2 using remote alarm configurations
- Remote trend recording possible
- First release: no synchronization of recipes



HMI redundancy - configuration

- Visualization redundancy is not bound to CODESYS HMI SL.
- Enabled within the general redundancy configuration
- Automatic enabling via libraries and generated code possible

 VisuRedundancy = VisuRedundancy, 3.5.17.0 (System)	VisuRedundancy	3.5.17.0
 RedundancyDataTransfer = RedundancyDataTransfer, 3.5.17.0 (System)	RDT	3.5.17.0
 NetBaseSrv = Net Base Services, 3.5.17.0 (3S - Smart Software Solutions GmbH)	NBS	3.5.17.0



Redundancy Configuration

Redundancy State

Applications

Files

Log

PLC Shell

Redundancy Settings

Registered Areas

Redundancy Link | General | Visualization

Enable


Switchover references

Use redundancy link configuration

IP address:Port used by clients on PLC 1: 0 . 0 . 0 . 0 : 8080

IP address:Port used by clients on PLC 2: 0 . 0 . 0 . 0 : 8080

Security

Secure communication 

Timeout

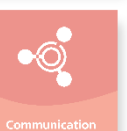
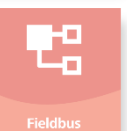
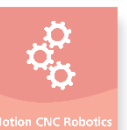
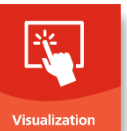
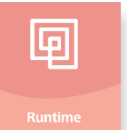
Receiving timeout (ms)

Transmission timeout (ms)

Options

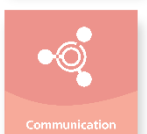
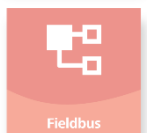
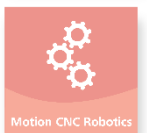
Seamless download

Advanced



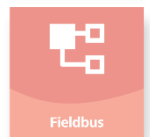
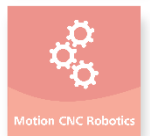
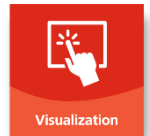
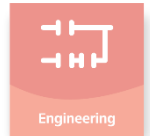
Improvements of Trend

- Interruptions in the trend recording (PLC Start/Stop) visible as gaps
- Possibility to stop the recording of single variables
- Dynamic limits for minimum / maximum of Y axes via IEC variables
- Trend legend with optional checkboxes to hide / show individual variables
- Possibility to reset the trend recording in the database
- Search / replace within the trend recording now possible



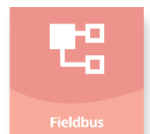
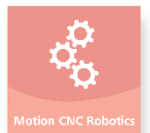
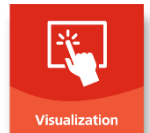
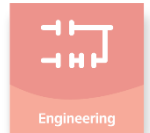
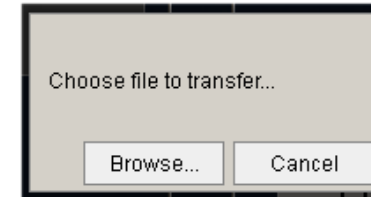
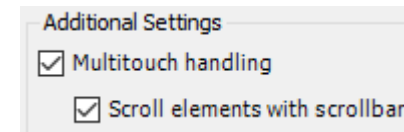
Improvements of alarm management

- **Possibility to readout all information of a selected alarm**
Both active and historical alarms
- **Complete alarm record can be reset via IEC application**



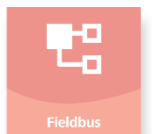
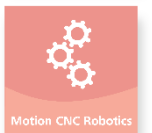
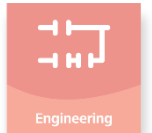
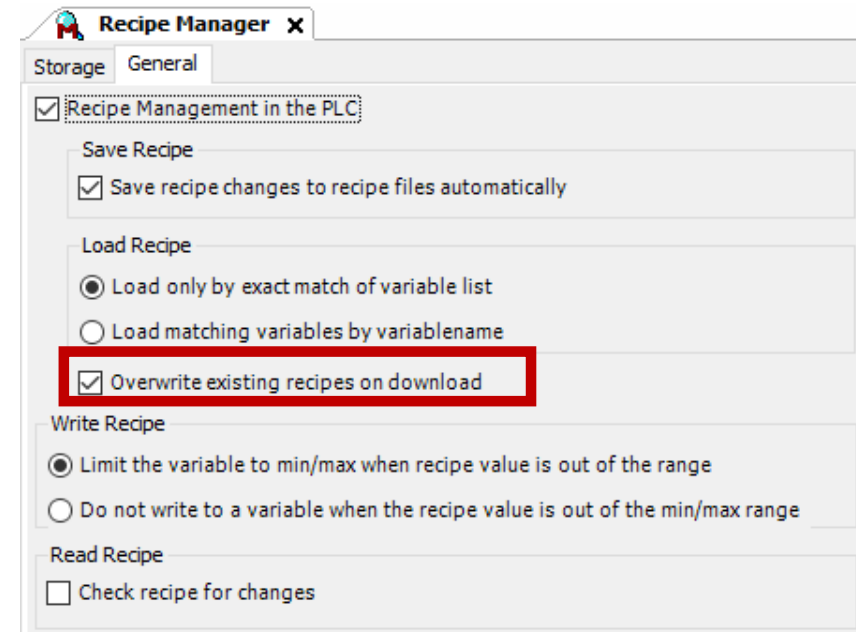
Further improvements

- **Support of the LDATE, LTOD, LDT, LTIME data types within visualization, alarm management, and recipe management**
 - Support in the Date and Date / Time Picker elements as well as in the formatted output / input with %t
 - Support of alarm conditions and latch variables
 - Support of variables in recipe definitions
- **Option to display scrollbars for scrollable elements like frame, table, combo box and alarm table when "Multitouch handling" is enabled.**
- **WebVisu FileTransfer - dialogs for the file transfer can be customized in size and design.**



Further improvements

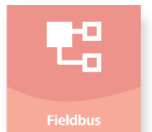
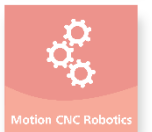
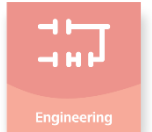
- **Interface/callback:** For tracking all inputs on elements
- **New format string for TIME variables to enter REAL values**
Examples:
 - %t[hh4] or %t[HH4], hours with 4 decimal places
 - %t[mm2] or %t[m2], minutes with 2 decimal places, e.g. 40.25 minutes
 - %t[ss0], seconds without decimal places.
- **Recipe management: new option**
→ **Recipes are / are not overwritten during download.**



Further improvements

- **Output of the number of used variables within all visualizations**

Metric	Size	Unit
Size of User Code	795280	Byte
Application	795280	Byte
Variables used in visualizations	320	Variables
Application	320	Variables



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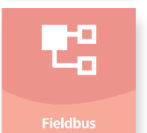
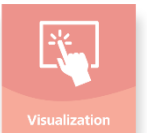
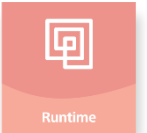
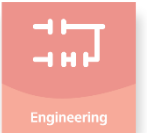
Fieldbus

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Communication

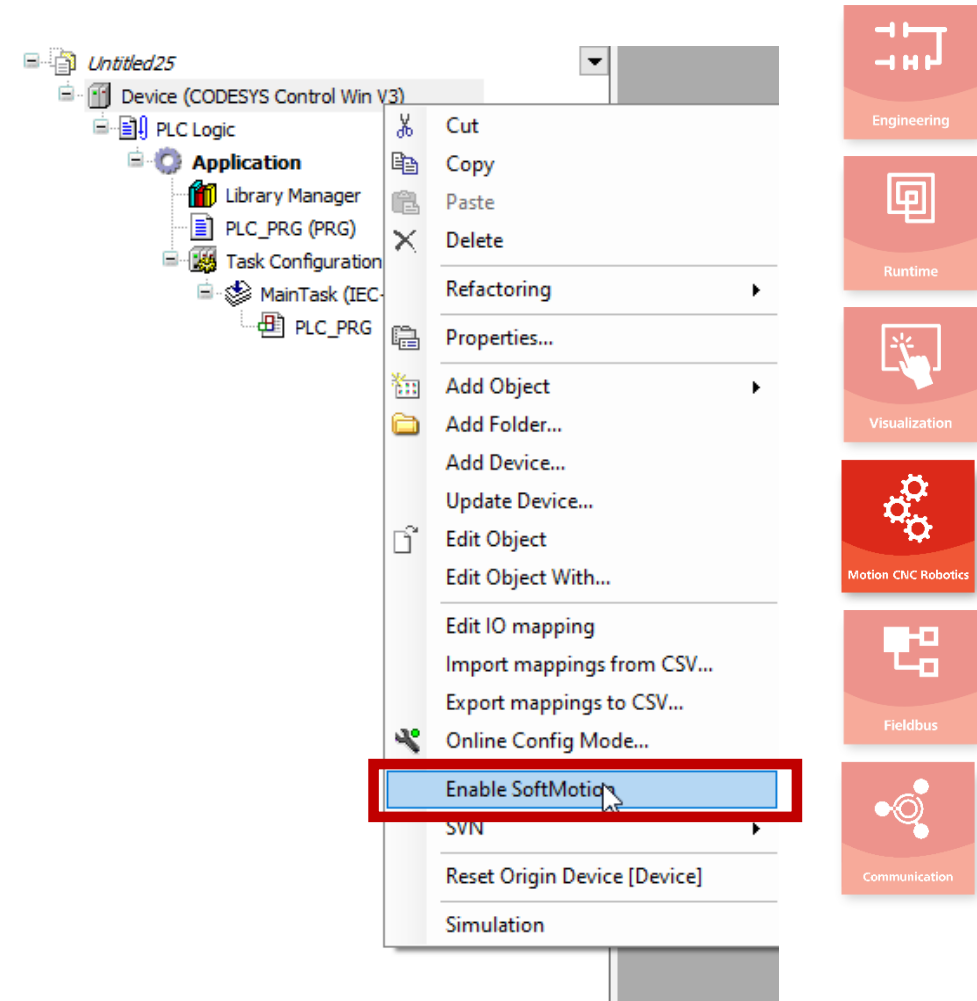
Overview

- **SoftMotion on Standard PLCs**
- **Robotics improvements**
- **New supported drives**



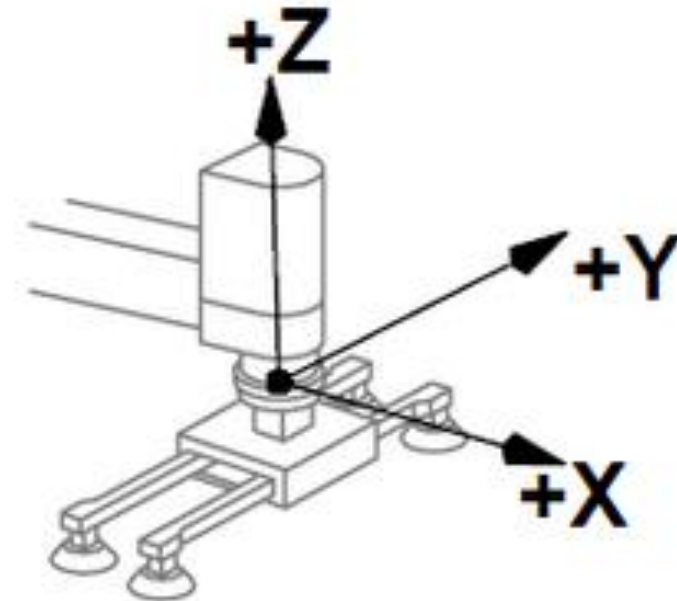
SoftMotion on Standard PLCs

- **Previously: SoftMotion only on devices with special target type = 0x1006**
- **New: SoftMotion can be run on all PLCs.**
- **Activation via new command "Enable SoftMotion"**
 → SoftMotion objects (CAM editor, CNC editor, axis groups) can now also be inserted on standard PLCs.
- **Advantage for users: easier upgrade**
 - of CODESYS compatible devices
 - of SoftPLCs from the CODESYS Store ("SL Runtimes")



Robotics improvements

- **Improved jogging**
 - Jogging = moving robot in manual mode
 - Improved orientation jogging:
Robot rotation more predictable
 - Fixing of numerous bugs
 - Improvement of test coverage
 - Improved documentation and error messages
- Note: SMC_GroupJog2 replaces SMC_GroupJog
(will be discontinued)



Engineering



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Motion CNC Robotics



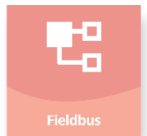
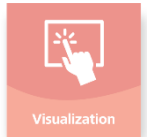
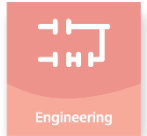
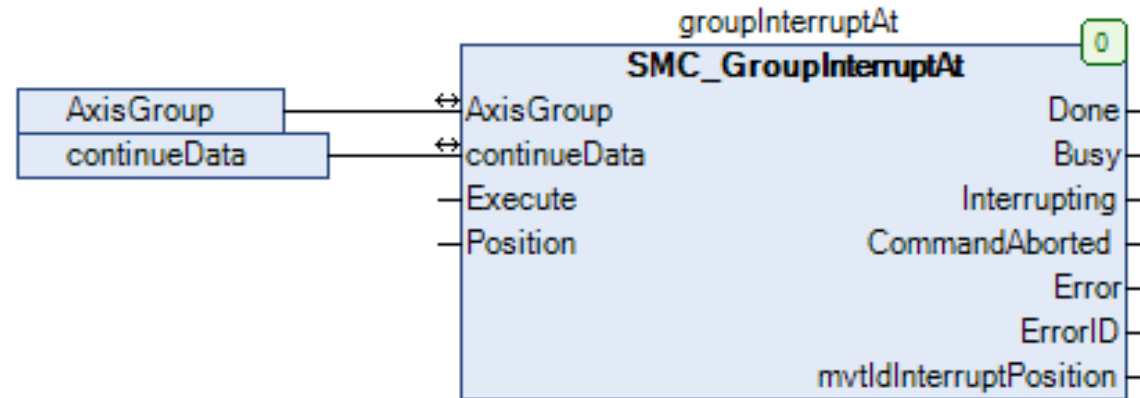
Fieldbus



Communication

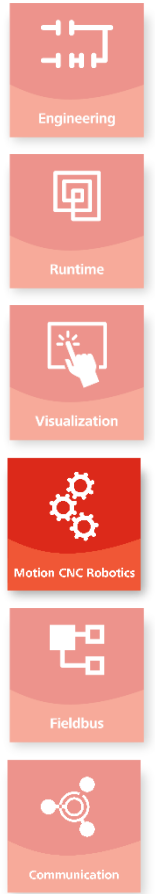
Robotics improvements

- **SMC_GroupInterruptAt**
 - Stopping at a certain position on the path
 - Otherwise like SMC_GroupInterrupt (pausing on the path)



New supported drives

- Bosch Rexroth IndraDrive CS
- Delta Remote IO
- Delta ASDA A3/B3
- Beckhoff EL7041/7047



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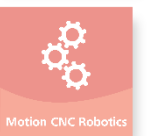
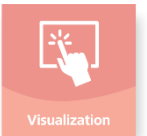
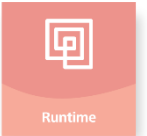
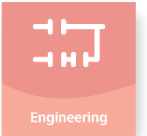
Fieldbus

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Communication

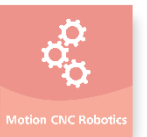
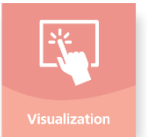
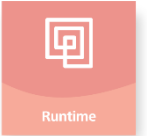
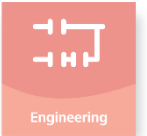
Overview

- **General improvements**
- **EtherNet/IP**
- **CAN / CANopen / J1939**
- **EtherCAT**
- **PROFINET**
- **MODBUS**



General improvements

- **Implicitly generated fieldbus task:**
 - Warning when deleted
 - Easy way for restoring deleted task



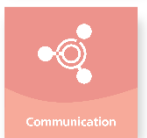
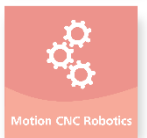
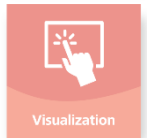
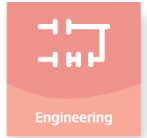
EtherNet/IP

▪ Scanner

- LargeForwardOpen for Scanner and Adapter:
Up to 65527 bytes per connection (before: 512 bytes)!
- EtherNet/IP Scanner:
Possibility of enabling filling bytes in I/O mapping
- Stability improvements for multiple connections per slave
- GUI: Many bug fixes and performance improvements
→ Update recommended!

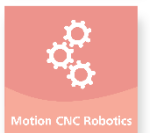
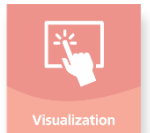
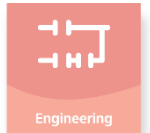
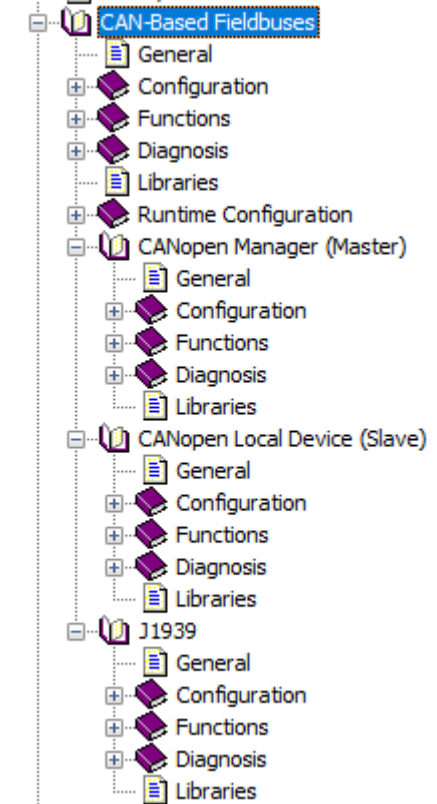
▪ Adapter

- Possibility for sending outputs on start of bus cycle:
Possible reason for doing so: less Jitter
- Extension of Ethernet Link Object:
Conformance test with 1 GBit possible



CAN (CANopen/J1939)

- **General rework of online help with focus on diagnosis**
 - New structure: Configuration, Functions, Libraries, Diagnosis
 - Diagnosis chapter added
 - Diagnosis in application
 - Diagnosis in user interface
 - Troubleshooting



CAN (CANopen/J1939)

Troubleshooting

CANbus

Problem	Possible Solution
The CANbus is red in the device tree directly after the application download.	<p>Check the status page and logger page of the CAN bus. You will find more information here.</p> <p>Possible causes:</p> <ul style="list-style-type: none"> The driver could not be opened: <ul style="list-style-type: none"> The network ID is set too large. In the CAN bus, a network ID was set for which there is no driver instance. If there are multiple CAN interfaces, then valid values for the network ID are only 0 and 1. The driver component was not loaded in the runtime. Check whether the CAN driver component has been loaded correctly (see the chapter "Configuration"). The memory is insufficient. Opening the CAN driver requires memory. Too little memory may be available. A bus error has occurred: <ul style="list-style-type: none"> The CAN chip signals a bus error. See the chapter "Diagnosis of Hardware Failures".

Diagnosis of Hardware Failures

Most CAN problems are traced back to incorrect wiring or faulty CAN devices. Potential errors include the following:

- Missing or incorrectly dimensioned terminal resistors
The bus has to be terminated exactly with a 120 Ω terminal resistance at the beginning and at the end.
- Different baud rates
All subscribers have to use the same baud rate.
- Short circuit between CANLow, CANHigh, CANGround, V+
- CANLow and CANHigh interchanged
- Different lengths of CANHigh and CANLow
- CANHigh and CANLow are not a twisted pair. As a result, signals can be interrupted more easily.
- Different grounding sources for CANGround
- Two-sided grounding of the CAN bus cable
When both ends of the shielding of the CAN bus cable are grounded, grounding loops can form which can cause interruptions.
- Bus cable too long
The maximum bus length depends on the set baud rate (see table).

Bit Rate	Cable Length
10 kbps	6.7 km
20 kbps	3.3 km
50 kbps	1.0 km
125 kbps	500 m
250 kbps	250 m
500 kbps	125 m
1 Mbps	25 m

Detecting hardware failures



Engineering



Runtime



Visualization



Motion CNC Robotics



Fieldbus

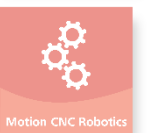
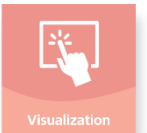
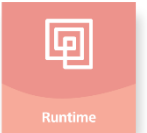
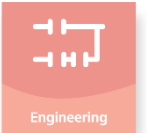


Communication

CAN (CANopen/J1939)

▪ Modularization

- Stack library placeholders:
Now part of the CANopenManager, CANopenSlave, and J1939Manager device
- Using new protocol stack:
Before: „Update device“ for PLC necessary → New runtime required
New: „Update device“ on the corresponding stack device (e.g. CANopenManager) possible



CANopen

- **CANopen Manager**

- Improved COB-ID collision detection and intelligent suggestions
 - Additional check for EMCY, SYNC and TIME COB-ID
 - Check & Fix dialog suggests COB-ID formulas where possible.

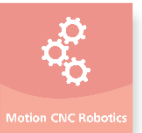
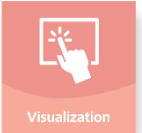
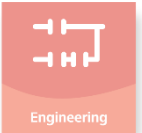
Name	Object	Bit length
<input checked="" type="checkbox"/> 16#1400: Receive PDO Communication Parameter	16#202	16
DigOutput8_1	16#6200:16#01	8
DigOutput8_2	16#6200:16#02	8
<input checked="" type="checkbox"/> 16#1401: Receive PDO Communication Parameter	16#202	64
Write Analogue Output 1	16#6411:16#01	16
Write Analogue Output 2	16#6411:16#02	16
Write Analogue Output 3	16#6411:16#03	16
Write Analogue Output 4	16#6411:16#04	16



Device name	Node-ID	Object	Formula	Conflicted COB-ID	Automatic Suggestion
BK5120	1	PDO 16#1400	16#202	16#00000202	<input type="text" value="\$NODEID+16#200"/>
BK5120	1	PDO 16#1401	16#202	16#00000202	<input type="text" value="\$NODEID+16#300"/>

- **CANopen Slave**

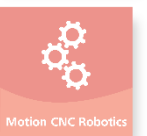
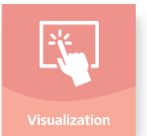
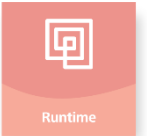
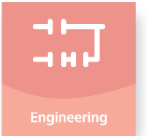
- PDO/SRDO communication settings of I/O areas can be edited.



J1939

- **Import function for DBC**

- Proprietary file format from Vector Informatik for defining CAN messages and ECUs
- Widely used by Commercial Vehicle Manufacturers
- Different use cases (see following slides)



J1939

Use case 1: Import a complete network

The image illustrates the steps to import a complete network in CODESYS:

- Import DBC File:** In the 'Application' tree, right-click and select 'Import DBC File...'.
- DBC content selection:** A dialog box showing a list of components to import. The 'TECU' (Transmission ECU) is selected.
- TECU Configuration:** The 'TECU' configuration window is shown with 'SAE J1939' selected and 'ECU NAME' set to '300E8A9344E'.
- Find Table:** A table listing variables and their mappings for the imported network.

Variable	Mapping	Channel	Address	Type	Unit	Description
TCFG2_TECU	TransTargetLimit	TransTargetLimit	%NW292	UBINT	mm	
TCFG_TECU	NumberOfReverse...	NumberOfReverseGearRatios	%M586	USINT		
	NumberOfForward...	NumberOfForwardGearRatios	%M587	USINT		
	TransGearRatio	TransGearRatio	%D147	REAL		
SOFT	NbrOfSwIdent...	NbrOfSwIdentificationFields	%M592	USINT	steps	
	SoftwareID_1	SoftwareID1	%M593	USINT		
	SoftwareID_2	SoftwareID2	%M594	USINT		
	SoftwareID_3	SoftwareID3	%M595	USINT		
ETC7_TECU	TransRangeD...	TransRangeDisplayBankState	%M596	USINT		
	TransRangeD...	TransRangeDisplayBankState	%M597	USINT		
	TransReadyForBra...	TransReadyForRelease	%M598	USINT		
	ActiveShiftConsol...	ActiveShiftConsoleIndicator	%M599	USINT		
	TransEngCrankEnab...	TransEngCrankEnable	%M600	USINT		
	TransShiftInhibit...	TransShiftInhibitIndicator	%M601	USINT		
	TransModeIndicator	TransModeIndicator	%M602	USINT		
	TransModeIndicator	TransModeIndicator	%M603	USINT		
	TransModeIndicator	TransModeIndicator	%M604	USINT		
	TransModeIndicator	TransModeIndicator	%M605	USINT		
	TransRqdGearFee...	TransRqdGearFeedback	%NW303	INT		
ETC2_TECU	TransSelectedGear	TransSelectedGear	%NW304	INT		
	TransActualGearRat...	TransActualGearRatios	%D153	REAL		
	TransCurrentGear	TransCurrentGear	%NW308	INT		
	TransRqdRange	TransRqdRange	%NW309	USINT		
	TransCurrentRange	TransCurrentRange	%NW310	USINT		
ETC1_TECU						
ECU20						
DM5						
DM4						
DM25						
DM24						
TRF1_TECU						



Engineering



Runtime



Visualization



Motion CNC Robotics



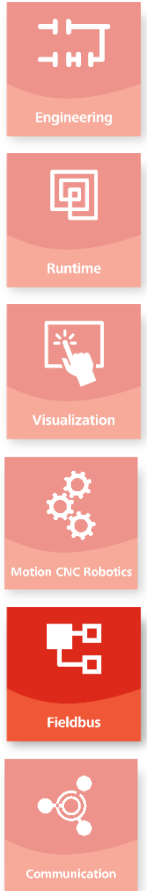
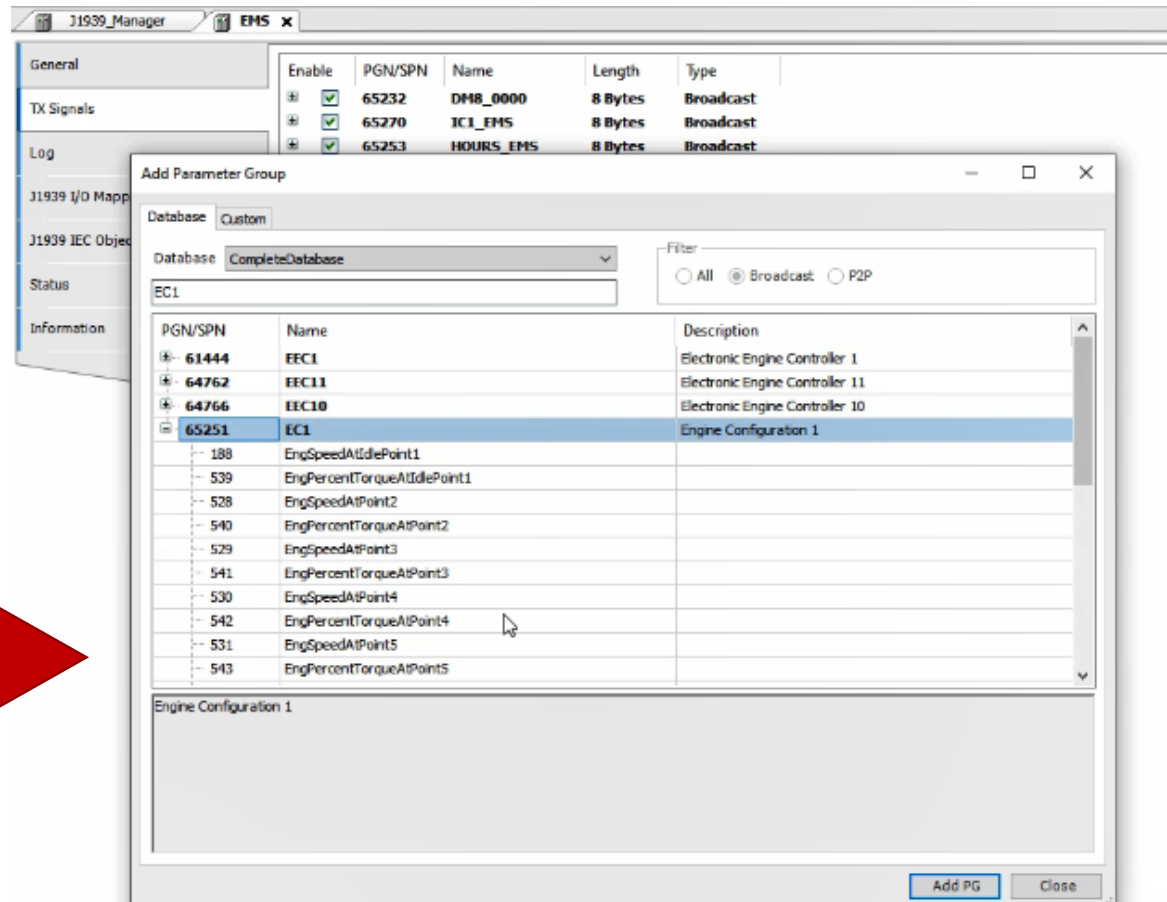
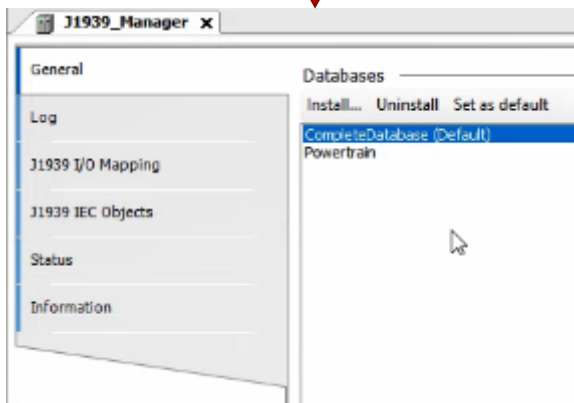
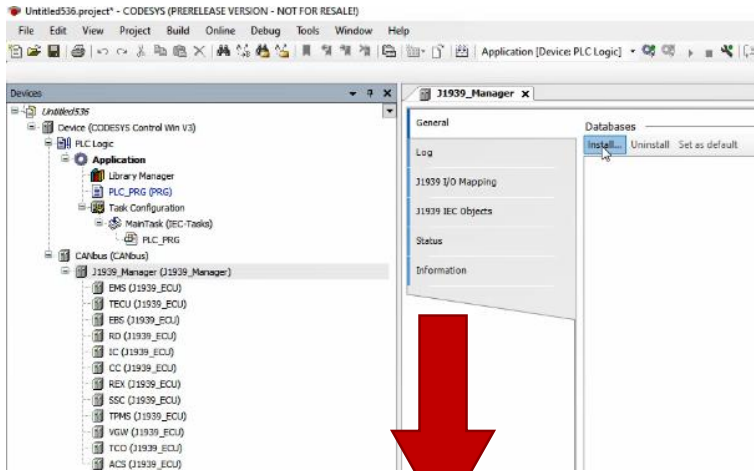
Fieldbus



Communication

J1939

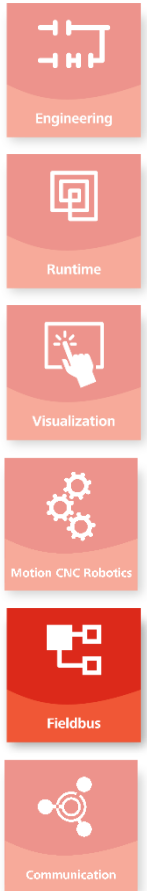
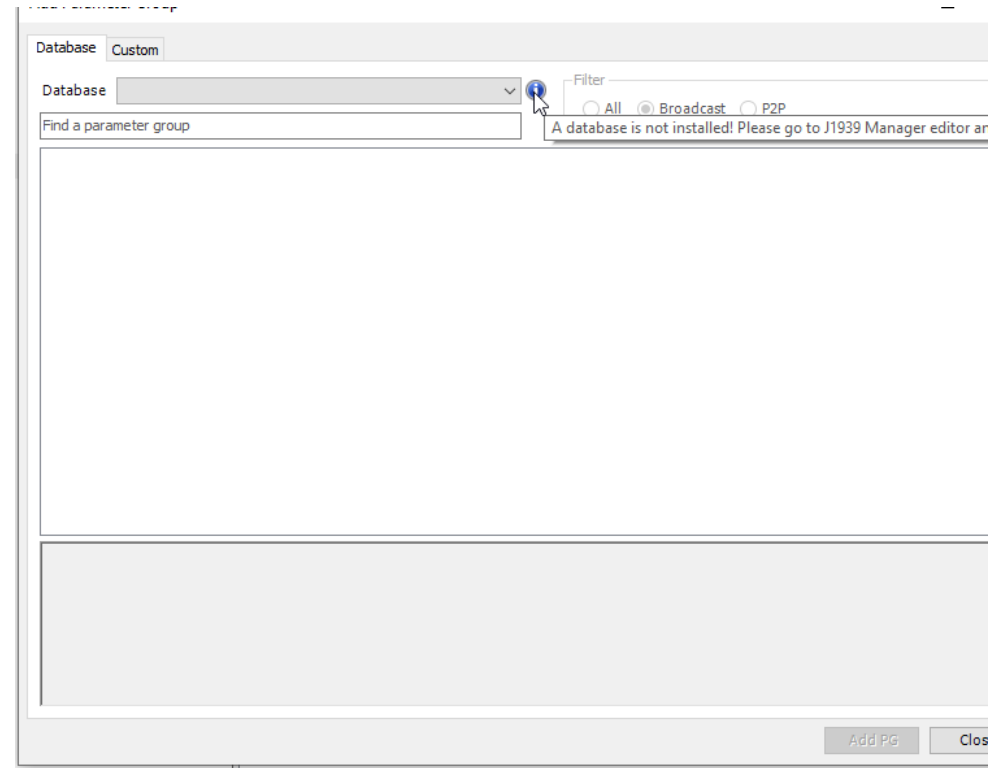
Use case 2: Install as database



J1939

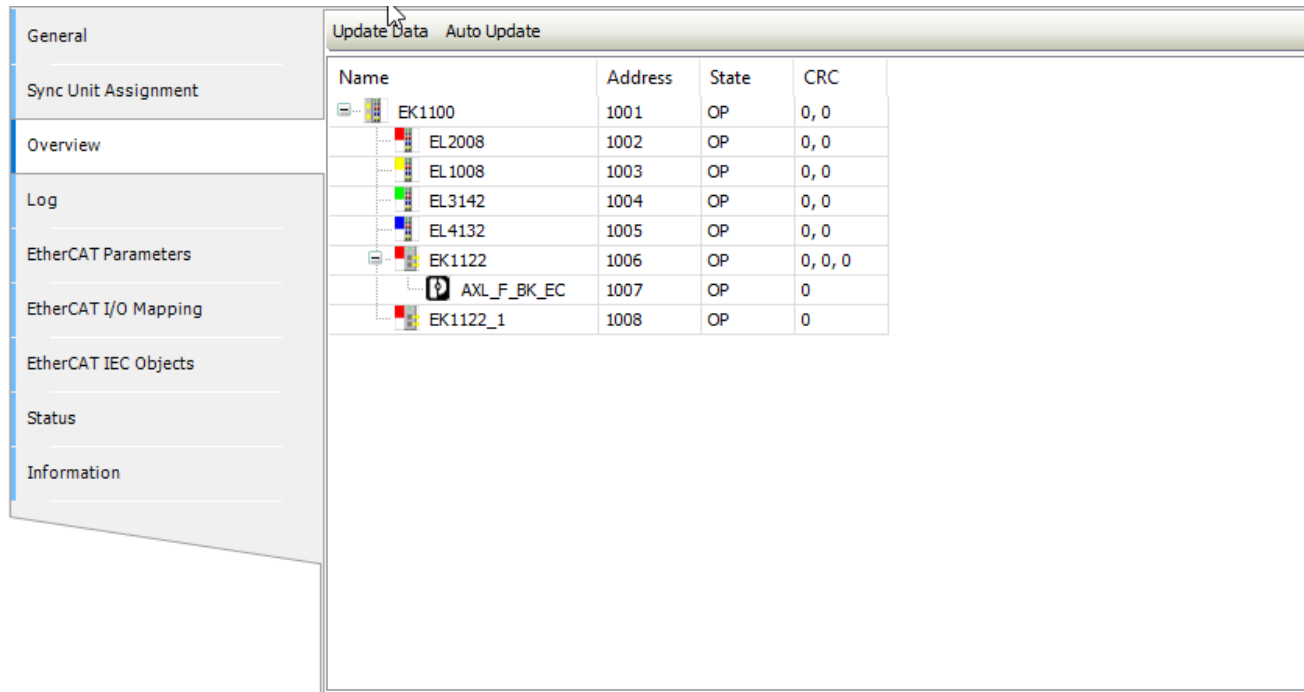
- **Removal of standard database**
 - Tooltip and online help notice the user!
 - User has to buy a DBC database e.g. from <https://www.csselectronics.com/>

Discount Code (5%):
J1939DBC_CODESYS



EtherCAT

- Online page shows Link-Status
- Routing of EoE
- Overview page for device status



Name	Address	State	CRC
EK1100	1001	OP	0, 0
EL2008	1002	OP	0, 0
EL1008	1003	OP	0, 0
EL3142	1004	OP	0, 0
EL4132	1005	OP	0, 0
EK1122	1006	OP	0, 0, 0
AXL_F_BK_EC	1007	OP	0
EK1122_1	1008	OP	0



Engineering



Runtime



Visualization



Motion CNC Robotics



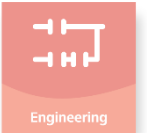
Fieldbus



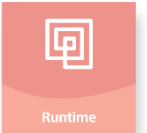
Communication

PROFINET

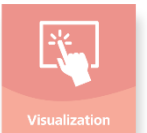
- **Performance optimizations**
Up to 40% lower bus cycle times
- **Support dual- / multi-port Ethernet interfaces**
→ Build controllers and devices with up to 8 Ethernet ports, e.g. for „Daisy Chain“ use case
- **Create PROFINET Device *.devdesc from GSDML**
→ No more manual steps for manufacturers of PROFINET Device



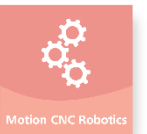
Engineering



Runtime



Visualization



Motion CNC Robotics



Fieldbus



Communication

PROFINET

- **PROFINET Device: programmatic configuration**
 - No Device-objects in static device tree
 - Completely programmatic, function block-based configuration (Library „ProfinetDeviceConfig“)

```
12  VAR
13     pnDevice : ProfinetDeviceConfig.ProfinetDeviceInstance;
14     deviceIdent : ProfinetDeviceConfig.DeviceIdentification;
15
16  //Startup:
17  IF (NOT pnDevice.xInit) THEN
18     deviceIdent.deviceID := 16#1017;      // Device Config
19     deviceIdent.vendorID := 16#02CC;
20     //...
21     pnDevice.Plug(in32);      //Plug Modules
22     pnDevice.Plug(out32x8);
23     pnDevice.Plug(out32_param);
24     //...
25     pnDevice.ConfigureDevice(interfaceName, deviceIdent); //Configure
26
27  ELSIF (NOT (pnDevice.xStartup OR pnDevice.xOnline)) THEN
28     pnDevice.Start();
29  END_IF
30
31  //Acyclic services of device:
32  pnDevice.ProcessServices();
```



Engineering



Runtime



Visualization



Motion CNC Robotics



Fieldbus



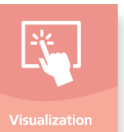
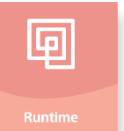
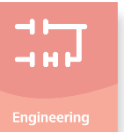
Communication

PROFINET

- **IO-Link integration**
 - Editor for settings of IO-Link Device (IODD based)
 - Pre-processed IO data
 - Diagnosis with textual information from IODD
 - Scan / import of IO-Link sensors

The screenshot displays the CODESYS software interface for configuring an IO-Link device. On the left, the 'Devices' tree shows a project named 'IOL_Example' containing a 'Device [connected] (CODESYS Control RTE V3 x64)'. Underneath, it lists 'Ethernet (Ethernet)' and 'PN_Controller (PN-Controller)'. The PN controller includes several modules: 'FW_4_90 (FW 4.90)', 'IM151_3_PN_HF_V7_0 (IM151-3 PN HF V7.0)', 'Danfoss_FC_PN (Danfoss FC PN)', 'al1400 (AL1402)', and 'al1400_1 (8 Ports)'. The 'al1400_1' module contains 'IOLM (IO-Link Master Proxy 8P)' and four ports: 'X1_B_Port', 'X2_B_Port', 'X3_B_Port', and 'X4_B_Port'. Below these are 'IOLD_Port5 (IO-Link 32 I / 32 O E)' and 'IOLD_Port6 (IO-Link 32 I / 32 O E)'. The main window shows the configuration for 'OMT300_R200_series'. It includes a 'User role' dropdown set to 'Maintenance', radio buttons for 'Identification menu' and 'Parameter menu' (the latter is selected), and buttons for 'Set to Defaults' and 'Re'. A table lists the configuration parameters for the device:

Name	Value	Unit
Operation Parameter		
Switching Signal Channel 1		
SP1	250.0	mm
SP2	150.0	mm
Logic	High active - Not Inverted	
Mode	Window	
Hysteresis	Standard	
SSC1 Config - SP Offset	30.0	mm
Switching Signal Channel 2		
Teach-In		



MODBUS

MODBUS function block library

- Completely programmatic, function block-based configuration and communication
- Client + server
- TCP + serial
- Various examples in CODESYS Forge

The screenshot displays the CODESYS software interface for the ModbusFB library. The left sidebar shows the library structure, including 'Library Information', 'ModbusFB', 'Enums', and 'Function Blocks'. Under 'Function Blocks', there is a 'Client' folder containing several function blocks, with 'ClientRequestReadBits' selected. The main window shows the definition of the 'ClientRequestReadBits' function block, which includes the following parameters and outputs:

```
ClientRequestReadBits
- xExecute BOOL
- udiTimeOut UDINT
- rClient Client
- [uiUnitId UINT := 0]
- [udiReplyTimeout UDINT := (50 * 1000)]
- [uiMaxRetries UINT := 0]
- [uiStartItem UINT := 0]
- [uiQuantity UINT := 1]
- [pData POINTER TO ARRAY [0..0] OF BOOL := 0]
      BOOL xDone
      BOOL xBusy
      BOOL xError
      Error eErrorID
      ExceptionCodes eException
      UINT uiRetryCnt
```



Engineering



Runtime



Visualization



Motion CNC Robotics



Fieldbus



Communication

1

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3

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4

Motion CNC Robotics

5

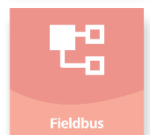
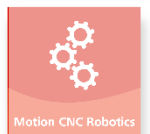
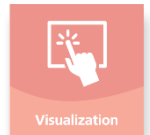
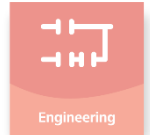
Fieldbus

6

Communication

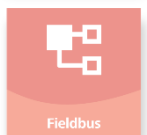
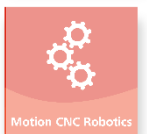
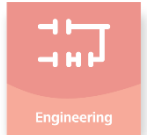
Overview

- **OPC UA Server/Client improvements**
- **OPC UA PubSub communication**
- **IIoT Library Bundle improvements**



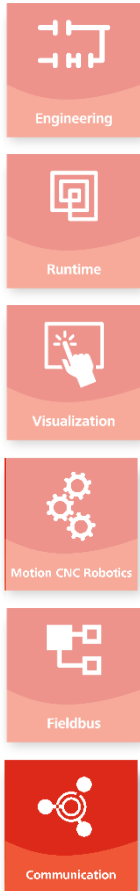
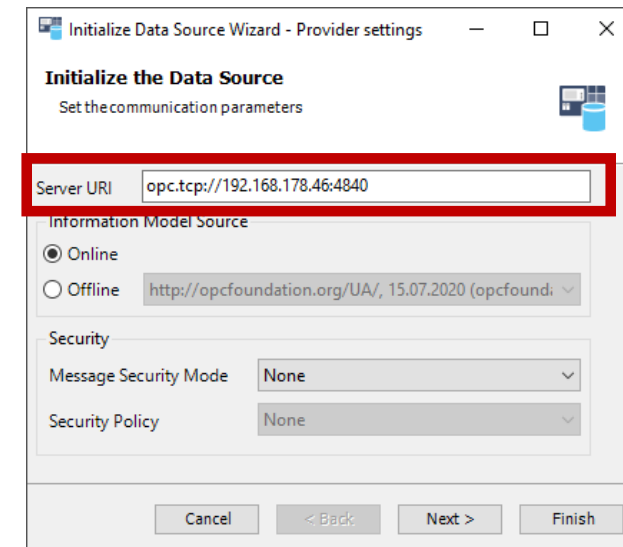
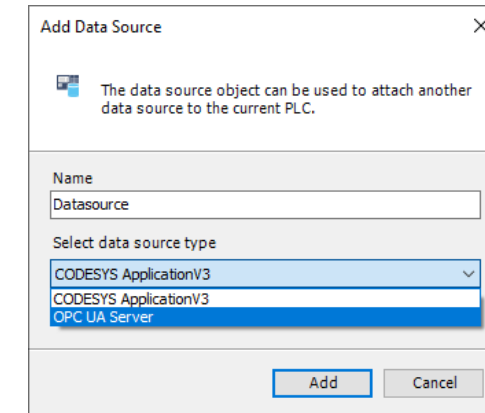
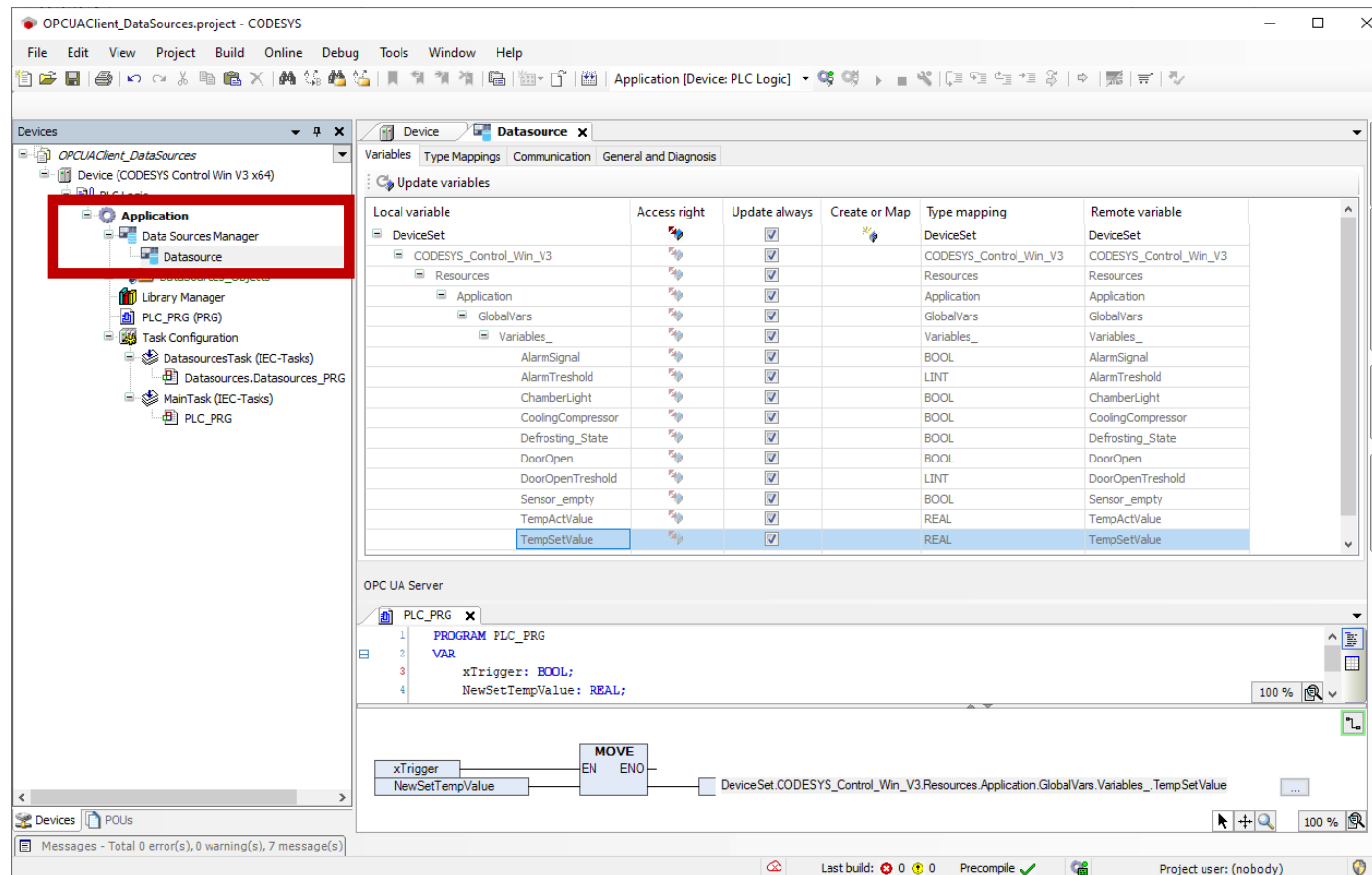
OPC UA Server/Client improvements

- **Support of OPC UA methods**
 - Use case: call functions and methods of IEC applications and start complex functional processes via OPC UA
- **Support of OPC UA alarms & conditions**
 - Use case: send and acknowledge alarms to and with a capable OPC UA client
 - Events signal a change of the alarm status to the client
 - The client uses methods to interact with a specific instance of an alarm or condition.
- **Implementation of new security profiles defined in OPC UA 1.04 (CDS-62076)**
 - Basic125Rsa15 and Basic256 message security policies have been deprecated.
 - Two new security profiles: Aes128Sha256RsaOaep (for medium security needs) and Aes256Sha256RsaPSS (for high security needs)



OPC UA Server/Client Improvements

- Support of OPC UA Client configuration via Data Sources

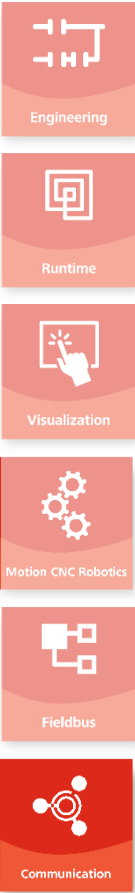


OPC UA information models / companion specifications

- Support of user-defined information models / companion specifications

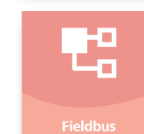
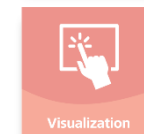
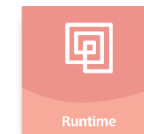
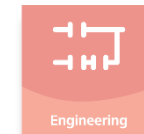
The screenshot illustrates the process of adding an OPC UA Information Model to a CODESYS project. The 'Add OPC UA Information Model' dialog is open, showing the name 'OPC_UA_Symbols' and the URI 'http://opcfoundation.org/UA/, 15.07.2020 (opcfoundation.org)'. The 'Communication Manager...' option is selected in the 'Add Object' menu. The 'OPC_UA_Symbols' information model is highlighted in the project tree. The 'Information Model' window shows the model's structure, and the 'Generate IEC declarations' button is highlighted. The 'OPC_UA_Symbols' window shows a table of mapped instances.

OPC UA Variable	OPC UA Type	Map or create	IEC Variable	IEC Type	Access Rights	Maximal
inst_1	TestRootObjectType		OPC_UA_Symbols.inst_1	TestRootObjectType		
inst_2	TestRootObjectType		OPC_UA_Symbols.inst_2	TestRootObjectType		
Inst2	TestRootObjectType		PLC_PRG.Inst2	TestRootObjectType		



IloT Library Bundle improvements

- **Extension of the functional scope**
 - Now with function blocks for data exchange with Google Cloud IoT Core
 - License for Google Cloud IoT Core Client SL included in the **IloT Libraries SL**





Thank you for your attention!

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